ISO 16329:2003-04 (E)

Ships and marine technology - Heading control systems for high-speed craft

Contents

Page

Foreword iv

1 Scope 1

2 Normative references 1

3 Terms and definitions 2

4 Performance 3
4.1 General 3
4.2 Constituents 4
4.3 Functional requirements 4
4.3.1 Introduction 4
4.3.2 Change-over from automatic to manual steering and vice versa 4
4.3.3 Operational controls including adjustment controls 5
4.3.4 Rudder angle limitation 6
4.3.5 Permitted yaw 6
4.3.6 Heading indication accuracy 6
4.3.7 Preset heading 6
4.3.8 Performing turns 6
4.3.9 Limiting of overshoot 6
4.3.10 Power supply 7
4.3.11 Alarms and signalling facilities 7
4.3.12 Transformation error 8
4.3.13 Heading stability 8
4.3.14 Disturbance to the magnetic compass 8
4.3.15 Interfaces 8
4.4 Safety precautions 8

5 Type testing 8
5.1 Testing and required results 8
5.2 Magnetic-compass safe-distance test 8
5.3 EMC and environmental test 9
5.4 Change-over from automatic to manual steering mode 9
5.5 Control characteristics 9
5.5.1 General 9
5.5.2 Heading-signal transformation accuracy 9
5.5.3 200° turn 9
5.5.4 Heading stability 10
5.5.5 Overshoot 10

6 Fall-back arrangements 10

7 Marking and identification 10

8 Information 11

Annex A (normative) Heading stability test under the conditions of disturbance 12

Annex B (normative) Craft-motion simulator 13

Annex C (informative) Example of heading stability test under the conditions of disturbance 15

Bibliography 20