

ISO 16329:2003-04 (E)

Ships and marine technology - Heading control systems for high-speed craft

| Contents | | Page |
|--|--|-------------|
| Foreword | | iv |
| 1 | Scope | 1 |
| 2 | Normative references | 1 |
| 3 | Terms and definitions | 2 |
| 4 | Performance | 3 |
| 4.1 | General | 3 |
| 4.2 | Constituents | 4 |
| 4.3 | Functional requirements | 4 |
| 4.3.1 | Introduction | 4 |
| 4.3.2 | Change-over from automatic to manual steering and vice versa | 4 |
| 4.3.3 | Operational controls including adjustment controls | 5 |
| 4.3.4 | Rudder angle limitation | 6 |
| 4.3.5 | Permitted yaw | 6 |
| 4.3.6 | Heading indication accuracy | 6 |
| 4.3.7 | Preset heading | 6 |
| 4.3.8 | Performing turns | 6 |
| 4.3.9 | Limiting of overshoot | 6 |
| 4.3.10 | Power supply | 7 |
| 4.3.11 | Alarms and signalling facilities | 7 |
| 4.3.12 | Transformation error | 8 |
| 4.3.13 | Heading stability | 8 |
| 4.3.14 | Disturbance to the magnetic compass | 8 |
| 4.3.15 | Interfaces | 8 |
| 4.4 | Safety precautions | 8 |
| 5 | Type testing | 8 |
| 5.1 | Testing and required results | 8 |
| 5.2 | Magnetic-compass safe-distance test | 8 |
| 5.3 | EMC and environmental test | 9 |
| 5.4 | Change-over from automatic to manual steering mode | 9 |
| 5.5 | Control characteristics | 9 |
| 5.5.1 | General | 9 |
| 5.5.2 | Heading-signal transformation accuracy | 9 |
| 5.5.3 | 200° turn | 9 |
| 5.5.4 | Heading stability | 10 |
| 5.5.5 | Overshoot | 10 |
| 6 | Fall-back arrangements | 10 |
| 7 | Marking and identification | 10 |
| 8 | Information | 11 |
| Annex A (normative) Heading stability test under the conditions of disturbance | | 12 |
| Annex B (normative) Craft-motion simulator | | 13 |
| Annex C (informative) Example of heading stability test under the conditions of disturbance | | 15 |
| Bibliography | | 20 |