

ISO 13643-1:2017-02 (E)

Ships and marine technology - Manoeuvring of ships - Part 1: General concepts, quantities and test conditions

Contents		Page
Foreword		iv
1	Scope	1
2	Normative references	1
3	Terms and definitions	1
4	Axis systems	2
4.1	General	2
4.2	Earth-fixed axis system	2
4.3	Ship-fixed axis system	2
5	Position coordinates	3
6	Angles	4
6.1	Angles of flow	4
6.1.1	Angle of attack	4
6.1.2	Drift angle	4
6.2	Angles of flow at parts of the ship	5
6.3	Eulerian angles	5
6.3.1	General	5
6.3.2	Nodal axes	5
6.3.3	Eulerian angles between earth-fixed and ship-fixed axis systems	7
7	General quantities	8
7.1	Physical quantities	8
7.2	Geometrical quantities	9
7.2.1	Symbols for manoeuvring	9
7.2.2	Additional and alternative indices	15
7.3	Mass quantities	17
7.4	Velocities and accelerations	18
7.5	Forces, moments and their coefficients	18
7.6	Control quantities	20
7.7	Propulsion	21
7.8	Derivatives	23
7.9	Dynamic stability	25
7.9.1	General	25
7.9.2	Dynamic stability of the coupled drift, yaw and roll motion (horizontal plane)	25
7.9.3	Dynamic stability of the coupled heave and pitch motion (vertical plane)	27
7.10	External disturbances	28
8	General test conditions, documentation	29
8.1	General	29
8.2	Environment	29
8.3	Ship	30
8.4	Test reports	31
8.5	Model tests	31
Annex A (informative)	Alphabetical list of symbols	33
Bibliography		41