ISO/TR 16158:2021-10 (E)

Space systems - Avoiding collisions among orbiting objects

Contents

Page

Foreword ..... **v**

Introduction ..... **vi**

1 Scope **1**

2 Normative references **1**

3 Terms and definitions **1**

4 Collision avoidance workflow **2**

5 Perceiving close approaches **2**

5.1 Orbit data 2

5.1.1 Inputs 2

5.1.2 Propagating all orbits over the interval of interest 3

5.2 Initial filtering 3

5.2.1 All against all 3

5.3 Eliminating infeasible conjunctions 3

5.3.1 General 3

5.3.2 Sieve 3

5.3.3 Toroidal elimination 4

5.3.4 Apogee-perigee filters 4

5.3.5 Statistical errors 4

6 Determining potential collisions for warning and further action (close approach screening) **4**

6.1 General 4

6.2 Symmetric keepout 4

6.3 Bounding volume keepout 5

6.4 Probability techniques 5

6.5 Maximum probability 7

6.6 Bounding volume based on probability 8

6.7 Comparison of techniques 10

7 Probability of survival **10**

7.1 General 10

7.2 Trending 11

7.3 Cumulative probability 11

7.4 Bayesian assessment 12

8 Additional information for judging courses of action **13**

8.1 General 13

8.2 Manoeuvre capability 13

8.3 Spacecraft characteristics 13

8.4 Quality of underlying orbit data 13

9 Consequence assessment **13**

9.1 General 13

9.2 Guidance for population risk 13

9.3 Traffic impacts 14

10 Requirements for warning and information for avoidance **14**

10.1 General 14

10.2 Orbit data 14

10.3 Minimum data required for warning of and avoiding collisions 15
10.4 Optional elements of information 15
11 Conjunction and collision assessment workflow and operational concept 16
Annex A (informative) **Relationship between combined object size, combined positional error, and maximum probability 19**
Annex B (informative) **Probability contour visualization 21**
Bibliography 31