DIN EN 16603-60-20:2014-12 (E)

Space engineering - Star sensor terminology and performance specification; English version EN 16603-60-20:2014

Contents

Page

Foreword 5

Introduction 6

1 Scope 7

2 Normative references 8

3 Terms, definitions and abbreviated terms 9

3.1 Terms from other standards 9

3.2 Terms specific to the present standard 9

3.3 Abbreviated terms 28

4 Functional requirements 30

4.1 Star sensor capabilities 30

4.1.1 Overview 30

4.1.2 Cartography 31

4.1.3 Star tracking 32

4.1.4 Autonomous star tracking 32

4.1.5 Autonomous attitude determination 33

4.1.6 Autonomous attitude tracking 34

4.1.7 Angular rate measurement 34

4.1.8 (Partial) image download 35

4.1.9 Sun survivability 35

4.2 Types of star sensors 36

4.2.1 Overview 36

4.2.2 Star camera 36

4.2.3 Star tracker 36

4.2.4 Autonomous star tracker 36

4.3 Reference frames 37

4.3.1 Overview 37

4.3.2 Provisions 37

4.4 On-board star catalogue 37

5 Performance requirements 39

5.1 Use of the statistical ensemble 39
5.1.1 Overview 39
5.1.2 Provisions 39
5.2 Use of simulations in verification methods 40
5.2.1 Overview 40
5.2.2 Provisions for single star performances 40
5.2.3 Provisions for quaternion performances 40
5.3 Confidence level 40
5.4 General performance conditions 41
5.5 General performance metrics 42
5.5.1 Overview 42
5.5.2 Bias 42
5.5.3 Thermo elastic error 43
5.5.4 FOV spatial error 44
5.5.5 Pixel spatial error 45
5.5.6 Temporal noise 45
5.5.7 Aberration of light 46
5.5.8 Measurement date error 47
5.5.9 Measured output bandwidth 47
5.6 Cartography 47
5.7 Star tracking 47
5.7.1 Additional performance conditions 47
5.7.2 Single star tracking maintenance probability 48
5.8 Autonomous star tracking 48
5.8.1 Additional performance conditions 48
5.8.2 Multiple star tracking maintenance level 48
5.9 Autonomous attitude determination 49
5.9.1 General 49
5.9.2 Additional performance conditions 49
5.9.3 Verification methods 50
5.9.4 Attitude determination probability 50
5.10 Autonomous attitude tracking 51
5.10.1 Additional performance conditions 51
5.10.2 Maintenance level of attitude tracking 52
5.10.3 Sensor settling time 53
5.11 Angular rate measurement 53
5.11.1 Additional performance conditions 53

5.11.2 Verification methods....53
5.12 Mathematical model....54

Bibliography....84

Figures

Figure 3-1: Star sensor elements – schematic....12
Figure 3-2: Example alignment reference frame....14
Figure 3-3: Boresight reference frame....15
Figure 3-4: Example of Inertial reference frame....15
Figure 3-5: Mechanical reference frame....16
Figure 3-6: Schematic illustration of reference frames....17
Figure 3-7: Stellar reference frame....17
Figure 3-8: Schematic timing diagram....19
Figure 3-9: Field of View....21
Figure 3-10: Aspect angle to planetary body or sun....22
Figure 4-1: Schematic generalized Star Sensor model....31
Figure B-1 : AME, MME schematic definition....61
Figure B-2 : RME Schematic Definition....62
Figure B-3 : MDE Schematic Definition....63
Figure B-4 : Rotational and directional Error Geometry....64
Figure F-1 : Angle rotation sequence....79
Figure H-1 : Example of detailed data sheet....83

Tables

Table C-1 : Minimum and optional capabilities for star sensors....69
Table D-1 : Measurement error metrics....71
Table D-2 : Star Position measurement error metrics....71
Table E-1 : Minimum number of simulations to verify a performance at performance confidence level P_C to an estimation confidence level of 95 %....76
Table G-1 : Contributing error sources....80