

E DIN EN 16603-40-07:2019-06 (E)

Erscheinungsdatum: 2019-05-10

Space engineering - Part 40-07: Software modelling platform; English version prEN 16603-40-07:2019

Table of contents

European Foreword.....	6
Introduction.....	7
1 Scope.....	8
2 Normative references.....	10
3 Terms, definitions and abbreviated terms.....	11
3.1 Terms from other standards.....	11
3.2 Terms specific to the present standard	11
3.3 Abbreviated terms.....	15
3.4 Nomenclature	15
4 Principles	16
4.1 Objectives.....	16
4.2 Common Concepts and common types	16
4.3 Architecture	17
4.4 Time handling principle.....	18
4.5 Simulation lifecycle	19
4.6 Simulation method	20
4.6.1 Discrete-event simulation (DES)	20
4.6.2 Parallelization and distribution.....	21
4.6.3 Inter component communication	21
4.7 Models, Services and Components	22
4.7.1 Objects.....	22
4.7.2 Components.....	23
4.7.3 Models and Services.....	24
4.8 Publication and Persistence.....	25
4.9 Dynamic invocation.....	26
4.10 Components meta data	28
4.10.1 Catalogue	28
4.10.2 Package.....	29
4.10.3 Configuration.....	29

4.11	Model exchanges considerations	29
4.11.1	SMP Bundle	29
5	Interface Requirements.....	30
5.1	Common.....	30
5.1.1	Primitive Types specification	30
5.1.2	Time Kinds	32
5.1.3	Path string.....	33
5.1.4	Universally Unique Identifiers (UUID).....	34
5.1.5	Exception specification.....	34
5.2	Components and Objects interfaces	34
5.2.1	Object Specification (IObject).....	34
5.2.2	Component Specification	35
5.2.3	Aggregation.....	38
5.2.4	Composition.....	41
5.2.5	Events.....	43
5.2.6	Entry points.....	45
5.2.7	Dynamic Invocation.....	46
5.2.8	Persistence (IPersist).....	50
5.2.9	Failures	50
5.2.10	Field interfaces.....	51
5.2.11	Simulation Environments interface utilization	57
5.3	Simulation Environment interfaces.....	58
5.3.1	Service specification (IService)	58
5.3.2	Logger (ILogger interface).....	58
5.3.3	Time Keeper (ITimeKeeper).....	60
5.3.4	Scheduler (IScheduler)	62
5.3.5	Event Manager (IEventManager)	70
5.3.6	Resolver (IResolver)	73
5.3.7	Link Registry (ILinkRegistry)	74
5.3.8	Simulator (ISimulator)	76
5.3.9	Persistence	87
5.3.10	Publication	88
5.3.11	Type Registry.....	94
5.3.12	Component Factory (IFactory)	100
5.4	Meta data	101
5.4.1	Catalogue	101
5.4.2	Package.....	104

5.4.3 Configuration data.....	105
6 Implementation mapping	106
6.1 Catalogue to C++	106
6.1.1 Mapping templates.....	106
6.1.2 Namespaces and files.....	109
6.1.3 Element and Type Visibility Kind	109
6.1.4 Mapping of elements.....	109
6.1.5 Basic Value Types	118
6.1.6 Compound Value Types.....	119
6.1.7 Reference Types.....	121
6.2 Package to library.....	124
6.2.1 Mapping templates.....	124
6.2.2 Common to Unix and Windows	125
6.2.3 Unix (Shared object)	125
6.2.4 Addendum for Windows Dynamic Link Library (DLL)	127
6.2.5 SMP Bundle	127
Annex A (normative) Catalogue DRD	128
A.1 Catalogue DRD	128
A.1.1 Requirement identification and source document.....	128
A.1.2 Purpose and objective.....	128
A.2 Expected response	128
A.2.1 Scope and content.....	128
A.2.2 Special remarks	128
Annex B (normative) Package DRD	129
B.1 Package DRD.....	129
B.1.1 Requirement identification and source document.....	129
B.1.2 Purpose and objective.....	129
B.2 Expected response	129
B.2.1 Scope and content.....	129
B.2.2 Special remarks	129
Annex C (normative) Configuration DRD	130
C.1 Configuration DRD.....	130
C.1.1 Requirement identification and source document.....	130
C.1.2 Purpose and objective.....	130
C.2 Expected response	130
C.2.1 Scope and content.....	130

C.2.2	Special remarks	130
Annex D (normative) Manifest DRD	131	
D.1	Configuration DRD.....	131
D.1.1	Requirement identification and source document.....	131
D.1.2	Purpose and objective.....	131
D.2	Expected response	131
D.2.1	Scope and content	131
D.2.2	Special remarks	133
Bibliography.....	134	

Figures

Figure 4-1:	Common Concepts and Type System	17
Figure 4-2:	SMP Architecture	17
Figure 4-3:	SMP State machine.....	19
Figure 4-4:	Object mechanisms.....	23
Figure 4-5:	Overview of components hierarchy	23
Figure 4-6:	Component Mechanisms.....	24
Figure 4-7:	Sequence of calls for dynamic invocation	27

Tables

Table 4-1:	Overview of simulation states	20
Table 4-2:	ViewKind values	25
Table 5-1:	Primitive Types.....	30
Table 5-2:	Component states	36
Table 5-3:	Semantically equivalent types for connections.....	56
Table 5-4:	Default Log Message Kinds.....	58
Table 5-5:	Condition for emitting predefined global events	72
Table 6-1:	C++ declaration templates.....	106
Table 6-2:	C++ definition templates	108
Table 6-3:	C++ mapping for the Visibility kind attribute	109
Table 6-4:	C++ mapping without ByPointer attribute.....	111
Table 6-5:	C++ mapping for the Direction kind attribute.....	112
Table 6-6:	C++ mapping without ByPointer attribute.....	113
Table 6-7:	C++ mapping for the Operator attribute kinds	116
Table 6-8:	C++ declaration templates for packages.....	124
Table 6-9:	SMP Manifest Key	131