

DIN EN 17067:2019-03 (E)

Forestry machinery - Safety requirements on radio remote controls

Contents	Page
European foreword	4
Introduction	5
1 Scope	6
2 Normative references	7
3 Terms and definitions	8
4 Requirements for cableless control systems (CCS)	13
4.1 General	13
4.2 Minimum control functions	13
4.3 General Safe STOP (GSS)	13
4.4 Control elements	14
4.4.1 General requirements	14
4.4.2 Unintended activation	14
4.4.3 Latching control functions	14
4.4.4 Minimum requirements	14
4.5 Design principles for forestry cableless control systems	14
4.5.1 Protection against unintended activation	14
4.5.2 Ergonomics	15
4.6 Marking	15
4.7 Requirements for controls with dual or multiple functions	19
4.7.1 Dual function with hold-to-run control (shift button)	19
4.7.2 Multiple control functions with mode selector	19
4.8 Multiple operator control units	19
4.9 Multiple base stations	20
4.10 Response times	20
4.10.1 Start and stop of movement functions	20
4.10.2 Fault tolerating times	20
4.11 Safety functions	20
4.11.1 Minimum requirements for the performance level	20
4.11.2 Safety objectives	20
4.11.3 Monitoring and safety of the wireless connection	21
4.12 Prevention of unintentional start of a function that would lead to a hazardous movement	21
4.13 Environment requirements	21
4.13.1 Temperature range according to EN 60068-2-14 and EN 60068-2-1	21
4.13.2 Mechanical strength according to EN 60068-2-31	21
4.13.3 IP protection class according to EN 60529	21
4.13.4 Requirements for the electromagnetic compatibility (EMC)	21
4.14 Self-tests	22
4.15 Warning devices	22
4.16 Control outputs	22
4.17 Marking	22
4.17.1 General	22
4.17.2 Information on the remote station	23
4.17.3 Information on the base station	23
4.18 Instruction handbook	24
DIN EN 17067:2019-03 EN 17067:2018 (E) 4.18.1 General	24
4.18.2 Winches	26

4.18.3	Mobile yarders	26
4.18.4	Additional instructions for CCS integration in a wood chipper	26
5	Requirements for cableless control systems for logging winches - minimum scope of functions	26
6	Requirements for cable-less control systems for travelling functions	27
7	Requirements for cableless control systems for mobile yarders	29
7.1	General	29
7.2	Multiple operator control units	29
7.3	Transfer/Adopt function	29
7.4	Stop function	30
7.4.1	General	30
7.4.2	Passive stop - additional requirements	30
7.5	Marking	30
8	Requirements for cableless control systems for wood chippers	32
	Annex A (normative) Examples of permissible radio ranges of CCS for mobile yarders	35
A.1	Action ranges with long distance in automatic mode	35
A.2	Carriage controlled by the tower yarder	36
A.2.1	Without remote stations	36
A.2.2	With remote commands reaching the tower yarder	37
A.2.3	Remote commands reaching the tower yarder via external repeater	38
A.3	Carriage controlled by CCS	38
A.3.1	Remote commands reaching the tower yarder via a transceiver installed on the carriage	38
A.3.2	Remote commanded active self-propelled carriage	39
	Annex ZA (informative) Relationship between this European Standard and the Essential Requirements of EU Directive 2006/42/EC amended by Directive 2009/127/EC aimed to be covered	40
	Bibliography	42