

ISO 16610-30:2015-10 (E)

Geometrical product specifications (GPS) - Filtration - Part 30: Robust profile filters: Basic concepts

| Contents | | Page |
|--|----------------------------------|-------------|
| Foreword | | iv |
| Introduction | | vi |
| 1 | Scope | 1 |
| 2 | Normative references | 1 |
| 3 | Terms and definitions | 1 |
| 4 | Robustness | 5 |
| 4.1 | General | 5 |
| 4.2 | Metric-based methods | 6 |
| 4.3 | Statistical-based methods | 6 |
| 4.3.1 | General | 6 |
| 4.3.2 | M-estimator | 6 |
| 4.3.3 | Bayesian estimator | 6 |
| 4.4 | Pre-processing methods | 6 |
| 4.4.1 | General | 6 |
| 4.4.2 | Scale-space pre-processing | 7 |
| 4.4.3 | Wavelet pre-processing | 7 |
| Annex A (informative) Illustrative data sets -- Input of profile discontinuities | | 8 |
| Annex B (informative) Concept diagram | | 11 |
| Annex C (informative) Relationship to the filtration matrix model | | 12 |
| Annex D (informative) Relation to the GPS matrix model | | 13 |
| Bibliography | | 14 |