

ISO/TS 4210-10:2020 (E)

Cycles — Safety requirements for bicycles — Part 10: Safety requirements for electrically power assisted cycles (EPACs)

Contents

	Foreword
	Introduction
1	Scope
2	Normative references
3	Terms and definitions
4	Abbreviated terms
5	General requirements
5.1	Lighting systems, reflectors and warning device
5.2	Risk assessment
5.3	Significant hazards and safety functions
5.3.1	Significant hazards
5.3.2	Safety function for control system of EPACs
5.3.2.1	General
5.3.2.2	Requirements
5.3.2.2.1	Safety related parts of the mechanical, hydraulic control systems
5.3.2.2.2	Safety related parts of the electrical control systems
5.3.2.3	Verification of the safety functions
5.4	Prevention of unauthorized use
5.5	Failure mode
5.5.1	Requirement
5.5.2	Test method
6	Electrical requirements
6.1	Motor controller
6.2	Controls and symbols
6.3	Batteries
6.4	Battery charger
6.4.1	Requirements for proprietary system
6.4.2	Requirements for non-proprietary system
6.4.2.1	General
6.4.2.2	Protocol requirements
6.4.2.3	Mechanical requirements
6.4.3	Solutions for non-proprietary systems
6.5	Electric cables and couplers
6.6	Wiring
6.7	Protection against ingress of water (IP code)
6.8	Environmental and operational conditions
6.9	Mechanical strength of the electrical components
6.9.1	General
6.9.2	Function related shock test
6.9.3	Impact related shock test
6.10	Performance measurement
6.10.1	General
6.10.2	System based on maximum continuous rated power
6.10.2.1	Maximum speed for which the electric motor gives assistance
6.10.2.1.1	Requirements
6.10.2.1.2	Test method

- 6.10.2.1.2.1 Test conditions
- 6.10.2.1.2.2 Test procedure
- 6.10.2.2 Power management
 - 6.10.2.2.1 Requirements
 - 6.10.2.2.2 Test method
 - 6.10.2.2.2.1 Test conditions
 - 6.10.2.2.2.2 Test track
 - 6.10.2.2.2.3 Test procedure
- 6.10.2.3 Measurement of the maximum continuous rated power
- 6.10.3 System based on maximum assisted rate
 - 6.10.3.1 Maximum speed and assisted rate for which the electric motor gives assistance
 - 6.10.3.1.1 General
 - 6.10.3.1.2 Test method
 - 6.10.3.1.2.1 Test conditions
 - 6.10.3.1.2.2 Measuring method and calculation formulae
 - 6.10.3.1.2.3 Overview diagram of equipment for testing assisted rate
 - 6.10.3.1.2.4 Setting of test load
 - 6.10.3.1.2.5 Test procedure
- 6.11 Walk assistance mode
 - 6.11.1 Requirements
 - 6.11.2 Test method for EPAC with walk assistance mode
 - 6.11.2.1 Test conditions
 - 6.11.2.2 Test procedure
- 6.12 Electromagnetic compatibility (EMC)
 - 6.12.1 Requirement
- 6.13 Anti-tampering measure
 - 6.13.1 General
 - 6.13.2 Prevention of tampering of the motor
- 6.14 Thermal hazards
 - 6.14.1 Non-continuous contact surface
 - 6.14.2 Continuous contact surface
 - 6.14.3 Ambient temperature

7 Mechanical requirements

- 7.1 General
- 7.2 Brakes — Heat-resistance test
- 7.3 Handlebar and stem assembly — Lateral bending test
- 7.4 Handlebar stem — Forward bending test
- 7.5 Handlebar to handlebar stem — Torsional security test
- 7.6 Handlebar and stem assembly — Fatigue test
- 7.7 Frame — Impact test (falling mass)
- 7.8 Frame and front fork assembly — Impact test (falling frame)
- 7.9 Frame — Fatigue test with horizontal forces
- 7.10 Frame — Fatigue test with a vertical force
- 7.11 Front fork — Static bending test
- 7.12 Front fork — Rearward impact test
- 7.13 Front fork — Bending fatigue test plus rearward impact test
- 7.14 Seat-post — Fatigue test

8 Manufacturer's instructions

9 Marking

Annex A (normative) Electromagnetic compatibility of EPACs

- A.1 Type testing procedures
- A.2 EPAC requirements
 - A.2.1 General
 - A.2.2 Test plan
 - A.2.3 Broadband electromagnetic radiation from EPACs
 - A.2.3.1 Method of measurement
 - A.2.3.2 EPAC broadband limits
 - A.2.3.2.1 Limit for 10 m measurement distance
 - A.2.3.2.2 Limit for 3 m measurement distance
 - A.2.3.2.3 Requirement

- A.2.4 Narrowband electromagnetic radiation from EPACs
 - A.2.4.1 Method of measurement
 - A.2.4.2 EPAC narrowband limits
 - A.2.4.2.1 Limit for 10 m measurement distance
 - A.2.4.2.2 Limit for 3 m measurement distance
 - A.2.4.2.3 Requirement
- A.2.5 Overview of radiated emission limits for EPACs
- A.2.6 EPAC immunity to electromagnetic radiation
 - A.2.6.1 Method of testing
 - A.2.6.2 Performance criteria and monitoring
 - A.2.6.3 EPAC immunity test levels
- A.3 Method of measurement of radiated electromagnetic emissions from EPACs
 - A.3.1 General
 - A.3.2 Test location
 - A.3.3 Measuring equipment
 - A.3.4 Test setup
 - A.3.5 Test procedure and test method
 - A.3.6 Test requirements for broadband emissions
 - A.3.6.1 General
 - A.3.6.2 Detector
 - A.3.6.3 EPAC state during test
 - A.3.7 Test requirements for narrow-band emissions
 - A.3.7.1 General
 - A.3.7.2 Detector
 - A.3.7.3 EPAC state during test
- A.4 Methods of testing EPAC immunity to electromagnetic radiation
 - A.4.1 General
 - A.4.2 Test location
 - A.4.3 Test instrumentation
 - A.4.4 Test setup
 - A.4.5 Test procedure and test method
 - A.4.6 Test requirements
 - A.4.6.1 Frequency range, dwell time, polarisation, modulation
 - A.4.6.2 EPAC state during tests
 - A.4.6.3 Reference point and position of EPAC

Annex B (informative) Electromagnetic compatibility of ESAs

- B.1 Type testing procedures for ESAs
 - B.1.1 General
 - B.1.2 Presumption of EPAC conformity by testing individual ESAs
 - B.1.3 Testing of ESA as part of an EPAC
- B.2 ESA requirements
 - B.2.1 General
 - B.2.2 Test plan
 - B.2.3 Broadband electromagnetic radiation from ESAs
 - B.2.3.1 Method of measurement
 - B.2.3.2 ESA broadband limits
 - B.2.4 Narrowband electromagnetic radiation from ESAs
 - B.2.4.1 Method of measurement
 - B.2.4.2 ESA narrowband limits
 - B.2.5 Overview of radiated emission limits for ESAs
 - B.2.6 ESA immunity to electromagnetic radiation
 - B.2.6.1 Method of testing
 - B.2.6.2 Performance criteria and monitoring
 - B.2.6.3 ESA immunity test levels
- B.3 Method of measurement of radiated electromagnetic emissions from ESAs
 - B.3.1 General
 - B.3.2 Drive system component (usually non 12 V)
 - B.3.3 Simulator box
 - B.3.4 Test location
 - B.3.5 Measuring equipment
 - B.3.6 Test setup
 - B.3.6.1 12 V load components
 - B.3.6.2 Drive system components

- B.3.7 Test procedure and test method
- B.3.8 Test requirements for broadband emissions
 - B.3.8.1 General
 - B.3.8.2 Detector
 - B.3.8.3 ESA state during test
- B.3.9 Test requirements for narrow-band emissions
 - B.3.9.1 General
 - B.3.9.2 Detector
 - B.3.9.3 ESA state during test
- B.4 Methods of testing ESA immunity to electromagnetic radiation
 - B.4.1 General
 - B.4.2 Drive system component (usually non 12 V)
 - B.4.3 Simulator box
 - B.4.4 BCI test method, 20 MHz to 200 MHz frequency range
 - B.4.4.1 Test location
 - B.4.4.2 Test instrumentation
 - B.4.4.3 Test setup
 - B.4.4.3.1 12 V load components
 - B.4.4.3.2 Drive system components
 - B.4.4.4 Test procedure and test method
 - B.4.4.5 Test requirements
 - B.4.4.5.1 Frequency range, dwell time, modulation, ports under test
 - B.4.4.5.2 ESA state during tests
 - B.4.5 ALSE test method, 200 MHz to 2 000 MHz frequency range
 - B.4.5.1 Test location
 - B.4.5.2 Test instrumentation
 - B.4.5.3 Test setup
 - B.4.5.3.1 General
 - B.4.5.3.2 12 V load components
 - B.4.5.3.3 Drive system components
 - B.4.5.4 Test procedure and test method
 - B.4.5.5 Test requirements
 - B.4.5.5.1 Frequency range, dwell time, modulation, ESA orientations
 - B.4.5.5.2 ESA state during tests

Annex C (normative) The battery chargers for non-proprietary system

- C.1 General
- C.2 System A
 - C.2.1 System Configuration
 - C.2.1.1 System Diagram
 - C.2.1.1.1 Master unit
 - C.2.1.1.2 Logical unit
 - C.2.2 Functions
 - C.2.2.1 Dynamic attach and detach
 - C.2.2.2 Error management of the system
 - C.2.2.2.1 General
 - C.2.2.2.2 Definition of errors
 - C.2.2.2.3 Basic Error code
 - C.2.2.2.4 Error of over voltage and over current
 - C.2.2.2.5 Error of over temperature and under temperature
 - C.2.2.2.6 Error reporting
 - C.2.2.2.7 Error tables
 - C.2.3 Operating conditions
 - C.2.3.1 General
 - C.2.3.2 Latency tolerance messaging
 - C.2.4 Specifications (mechanical/electrical)
 - C.2.4.1 Charger inlet and charger connector
 - C.2.4.1.1 General
 - C.2.4.1.2 Charger connector
 - C.2.4.1.3 Charger inlet
 - C.2.4.1.4 Sample for the charger connector assembly
 - C.2.4.1.5 Function of charger inlet and charger connector
 - C.2.4.1.6 DC and PLC Terminals Specification
 - C.2.4.2 Cables

- C.2.4.2.1 Cable characteristics
- C.2.4.2.2 Cable IR drop
- C.2.4.2.3 PLC line
- C.2.4.2.4 Power line
- C.2.5 Communication media
 - C.2.5.1 PLC specification
 - C.2.5.2 Getting signals
 - C.2.5.3 Physical layer format
 - C.2.5.3.1 General
 - C.2.5.3.2 Frame format
 - C.2.5.3.3 Beacon
 - C.2.5.3.4 Acknowledge (ACK)
 - C.2.5.3.5 Description of format
 - C.2.5.3.6 Description of field
 - C.2.5.4 Data and waveform
 - C.2.5.4.1 General
 - C.2.5.4.2 BPSK
- C.2.6 Communication protocols
 - C.2.6.1 Information of communication for charging
 - C.2.6.1.1 General
 - C.2.6.1.2 Set charge mode
 - C.2.6.1.3 Operating information of EPAC
 - C.2.6.1.4 Operating Information
 - C.2.6.1.5 Optional information
 - C.2.6.1.6 Operating information page 2
 - C.2.6.1.7 Information of communication for charger
 - C.2.6.1.8 Operating information of charger
 - C.2.6.1.9 Operating information of charger:
 - C.2.6.1.10 Page code
 - C.2.6.2 Plug and play (PnP) command
 - C.2.6.2.1 General
 - C.2.6.2.2 Plug and play command table
 - C.2.6.3 Plug and play (PnP) command descriptor block
 - C.2.6.3.1 Command descriptor block (CDB) format for PnP
 - C.2.6.3.2 Address request reception (Code: 011b)
 - C.2.6.3.3 Address No(Code: 111b) command
 - C.2.6.3.4 Address set (Code: 101b)
 - C.2.6.3.5 Address request1(Code: 101b) command
 - C.2.6.3.6 Address request2(Code: 111b) command
 - C.2.6.3.7 Address acknowledge (Code: 011b) command
 - C.2.6.4 Standard command
 - C.2.6.4.1 Standard command list
 - C.2.6.5 Standard command descriptor block
 - C.2.6.5.1 Command descriptor block (CDB) format
 - C.2.6.5.2 TEST UNIT READY command descriptor block
 - C.2.6.5.3 INQUIRY command
 - C.2.6.5.4 DEVICE DETECTION Command
 - C.2.6.5.5 REQUEST SENSE command
 - C.2.6.5.6 START/STOP command
 - C.2.6.5.7 REQUEST DATA Command
 - C.2.6.5.7.1 General
 - C.2.6.5.7.2 Type of request
 - C.2.6.5.7.3 Sub operation code
 - C.2.6.5.7.4 Command relation table
 - C.2.6.5.8 SEND DATA Command
 - C.2.6.5.9 STOP DATA command
 - C.2.6.5.10 MODE SENSE command
 - C.2.6.5.10.1General
 - C.2.6.5.10.2Page control (PC)
 - C.2.6.5.10.3Page code
 - C.2.6.5.11 ACCESS DIRECT command
 - C.2.6.5.12 MODE SELECT command
 - C.2.6.5.13 ERROR REPORT command
 - C.2.6.5.14 The SEND DATA LARGE command

- C.2.6.6 Sequence
 - C.2.6.6.1 Heart beat
 - C.2.6.6.2 Sequence of devices detection
 - C.2.6.6.3 Communication Sequence
- C.3 System B
 - C.3.1 System configuration
 - C.3.1.1 System diagram
 - C.3.1.2 Multi-Master CAN network and data exchange principle
 - C.3.2 Functions
 - C.3.2.1 Dynamic attach and detach
 - C.3.3 Operating Condition
 - C.3.3.1 General
 - C.3.3.2 CAN frame timeout monitoring
 - C.3.4 Specification(mechanical/electrical)
 - C.3.4.1 Charger inlet and charger connector
 - C.3.4.2 Cable characteristics
 - C.3.5 Communication media
 - C.3.5.1 Communication — Physical layer specification
 - C.3.6 Communication protocol
 - C.3.6.1 General
 - C.3.6.2 CAN frames send by charger
 - C.3.6.2.1 Chrg_ErrorCode
 - C.3.6.2.2 Chrg_Heartbeat
 - C.3.6.2.3 Chrg_Measure
 - C.3.6.2.4 Chrg_NetworkManagement
 - C.3.6.2.5 Chrg_PropertiesAdmin
 - C.3.6.2.6 Chrg_PropElectrical
 - C.3.6.2.7 Chrg_PropertiesSwInfo
 - C.3.6.2.8 Chrg_ReqProperties
 - C.3.6.3 CAN frames send by EPAC
 - C.3.6.3.1 EPAC_ChargerControl1
 - C.3.6.3.2 EPAC_ErrorCode
 - C.3.6.3.3 EPAC_Heartbeat
 - C.3.6.3.4 EPAC_Measure
 - C.3.6.3.5 EPAC_NetworkManagement
 - C.3.6.3.6 EPAC_PropElectical
 - C.3.6.3.7 EPAC_PropertiesAdmin
 - C.3.6.3.8 EPAC_PropertiesSwInfo
 - C.3.6.3.9 EPAC_ReqProperties
 - C.3.6.3.10 EPAC_Status1
 - C.3.6.4 Sequence
 - C.3.6.4.1 Wake Up
 - C.3.6.4.2 Charging Configuration
 - C.3.6.4.3 Shutdown

Annex D (normative) Light, audible warning device, On/Off symbols

Annex E (informative) Environmental and operational conditions

- E.1 General
- E.2 Pollution degree (IEV 851-15-17)

Annex F (normative) Battery

- F.1 Nickel system batteries
- F.2 Lithium system batteries
 - F.2.1 Cells
 - F.2.2 General safety consideration of battery
 - F.2.3 Safety at intended use
 - F.2.3.1 General
 - F.2.3.2 Dewing
 - F.2.3.3 Thermal shock cycling
 - F.2.3.4 Thermoplastic materials exposed to sunlight
 - F.2.3.4.1 General
 - F.2.3.4.2 Requirement
 - F.2.4 Safety at reasonably foreseeable misuse

- F.2.4.1 External short-circuit**
- F.2.4.1.1 General**
- F.2.4.1.2 Evaluation 1**
- F.2.4.1.3 Evaluation 2**
- F.2.4.2 Free fall**
- F.2.4.3 Over-charging of battery**
- F.2.4.3.1 General**
- F.2.4.3.2 Evaluation 1**
- F.2.4.3.3 Evaluation 2**
- F.2.4.4 Vibration**
- F.2.4.5 Mechanical shock**
- F.2.5 Simulated vehicle accident**
- F.2.5.1 Crush test**
- F.2.5.2 Water immersion**
- F.2.5.3 Charging and discharging range**

Page count: 125