ISO/TS 19159-2:2016-04 (E)

Geographic information - Calibration and validation of remote sensing imagery sensors and data - Part 2: Lidar

Contents

Page

Foreword iv

Introduction v

1 Scope 1

2 Conformance 1

3 Normative references 1

4 Termsanddefinitions 1

5 Symbols and abbreviated terms 9
5.1 Abbreviated terms 9
5.2 Symbols 10
5.3 Conventions 10

6 Calibration 10
6.1 Project 10
6.2 Coordinate Reference Systems 11
6.2.1 General 11
6.2.2 Sensor frame - s 13
6.2.3 Body frame - b 13
6.2.4 Earth-centred, earth-fixed - e 14
6.2.5 Mapping frame - m 16
6.3 Transformations 16
6.3.1 General 16
6.3.2 Airborne laser scanner observation equation 17
6.3.3 Strip adjustment 18
6.4 Intensity 18
6.5 Error model 18
6.5.1 General 18
6.5.2 Trajectory positioning and orientation 19
6.5.3 Boresight error and misalignment matrix 19
6.5.4 Lever-arm 20
6.5.5 Scanner 20
6.5.6 Scanner assembly error 20
6.6 In-flight calibration 20
6.7 Residual strip errors 22
6.8 Validation 22

Annex A (normative) Abstract test suite 23

Annex B (normative) Data dictionary 25

Annex C (informative) Rotations 30

Bibliography 32