ISO 22133:2026-01 (E)

Road vehicles - Test object monitoring and control for active safety and automated/autonomous vehicle testing - Functional requirements, specifications and communication protocol

Contents

Page

Foreword ..... **vi**

Introduction ..... **vii**

1 Scope **1**

2 Normative references **1**

3 Terms and definitions **1**

4 Abbreviated terms **4**

5 Test scenario illustration **5**

6 General requirements and recommendations **6**
6.1 Function overview 6
6.2 Test object coordinate system 6
6.2.1 Vehicle 6
6.2.2 Moveable test objects other than vehicle 7
6.3 Test scenario coordinate system 9
6.3.1 Background info: tectonic/continental plate drift 9
6.3.2 Coordinate system – Tests on proving ground 9
6.3.3 Coordinate system – Test on other test areas 10
6.4 Time requirements 11
6.4.1 General time requirements 11
6.4.2 Time representation 11
6.4.3 Absolute time 11
6.4.4 Relative time 11
6.4.5 Time resolution 11
6.4.6 Time accuracy (and precision) 12
6.4.7 Time synchronization 12
6.4.8 Date synchronization 13
6.4.9 Network delay 13
6.5 Communication requirements, recommendations and permissions 14

7 Safety and risk assessment requirements and recommendations **15**
7.1 General 15
7.2 Local test object fence and global geofence 15
7.2.1 Common requirements and recommendations 15
7.2.2 Global geofence 15
7.2.3 Local test object fence 15

8 Communication security requirements **17**

9 Architecture and interfaces **17**
9.1 General 17
9.2 Control centre and test object states 18
9.2.1 General 18
9.2.2 Test objects state diagram 18
9.2.3 Test object state change conditions 20
9.2.4 Control centre state diagram 20
9.2.5 Control centre state change triggers 21
9.3 Communication setup 22
9.3.1 General 22

9.3.2 Test object discovery ... 23
9.3.3 TCP communication setup (control channel) ... 24
9.3.4 UDP communication setup (process channel) ... 25
9.3.5 File transfer protocol (FTP) ... 26
9.4 Control functionalities ... 26
9.4.1 Automated and non-automated drive ... 26
9.4.2 Remote control manoeuvring ... 27
9.5 Monitoring functionalities ... 28
9.5.1 Introduction to test object monitoring ... 28
9.5.2 Test object monitoring communication ... 28

10 Trajectory and scenario-based testing ... 29
10.1 Introduction to trajectory and scenario-based testing ... 29
10.2 Static trajectories ... 29
10.3 Dynamic trajectories ... 30
10.4 Scenario description languages ... 30

11 Functional requirements ... 31
11.1 Device interface description XML (DIDX) ... 31
11.2 Control centre requirements and recommendations ... 32
11.3 Stationary test object requirements ... 32
11.4 Moveable test object requirements and recommendations ... 32
11.5 Functions with behaviour description ... 33
11.5.1 Arm and disarm test object ... 33
11.5.2 Start a test ... 33
11.5.3 Emergency stop of test scenario (initiated by the CC) ... 34
11.5.4 Emergency stop of test scenario (upon request from test object) ... 35
11.5.5 Normal stop of test scenario ... 36
11.5.6 Normal stop by test object ... 37
11.5.7 Download static (pre-planned) trajectories ... 37
11.5.8 Cyclic monitor and heartbeat ... 38
11.5.9 Adaptive synchronization point ... 38
11.5.10 Remote control manoeuvring ... 41
11.5.11 Trigger and action ... 42

12 Message requirements ... 43
12.1 General ... 43
12.2 Message ... 43
12.2.1 Message structure ... 43
12.2.2 Sequential byte order ... 43
12.2.3 Message header ... 44
12.2.4 Message content ... 46
12.2.5 Message footer ... 47
12.2.6 Protocol tunnel ... 47
12.2.7 Vendor-specific messages ... 47
12.3 Definition of messages ... 47
12.3.1 Collective message overview ... 47
12.3.2 Trajectory object message - TRAJ (MsgID 0x0001) ... 49
12.3.3 Object setting message – OSEM (MsgID 0x0002) ... 53
12.3.4 Object action state change request message – OSTM (MsgID 0x0003) ... 60
12.3.5 Start message - STRT (MsgID 0x0004) ... 61
12.3.6 Heartbeat message – HEAB (MsgID 0x0005) ... 62
12.3.7 Monitor message – MONR (MsgID 0x0006) ... 63
12.3.8 Monitor message 2 – MONR2 (MsgID 0x0007) ... 68
12.3.9 GPS second of week roll over message – SOWM (MsgID 0x0008) ... 69
12.3.10 Synchronization point configuration message – SYPM (MsgID 0x000B) ... 70
12.3.11 Leader time to synchronization point message -LTSP (MsgID 0x000C) ... 71
12.3.12 Remote control manoeuvring message – RCMM (MsgID 0x000A) ... 71
12.3.13 Remote control manoeuvring message 2 – RCMM2 (MsgID 0x0016) ... 74
12.3.14 Trigger configuration message – TRCM (MsgID 0x0021) ... 77
12.3.15 Action configuration message – ACCM (MsgID 0x0022) ... 79
12.3.16 Trigger event occured message – TREO (MsgID 0x0023) ... 81

12.3.17 Execute action message – EXAC (MsgID 0x0024) 82
12.3.18 Cancel or delete trigger and action – CADE (MsgID 0x0025) 82
12.3.19 Action performed message – APEM (MsgID 0x0026) 83
12.3.20 Discovery request DREQ (MsgID 0x0010) 84
12.3.21 Discovery response DRES (MsgID 0x0011) 84
12.3.22 Parameter request message – PREQ (MsgID 0x0012) 85
12.3.23 Parameter response message PRES (MsgID 0x0013) 86
12.3.24 Geofence message GEOF (MsgID 0x0009) 87
12.3.25 General data message - GEDM (MsgID 0x0017) 89
12.3.26 General response message - GREM (MsgID 0x0018) 90
12.3.27 Dynamic position point message – DPPM (MsgID 0x0027) 91

Annex A (normative) **Trajectory file format** **93**

Annex B (informative) **Message footer checksum calculation** **96**

Annex C (informative) **Trigger and action** **99**

Annex D (normative) **Device interface description XML (DIDX)** **104**

Annex E (informative) **An overtake by a test object with dynamic position points (DPP)** **106**

Bibliography **116**