

ISO 7856:2025-06 (E)

Intelligent transport systems - Remote support for low speed automated driving systems (RS-LSADS) - Performance requirements, system requirements and performance test procedures

Contents

Page

- Foreword..... v
- Introduction..... vi
- 1 Scope..... 1
- 2 Normative references..... 1
- 3 Terms and definitions..... 1
- 4 Symbols and abbreviated terms..... 3
 - 4.1 Symbols..... 3
 - 4.2 Abbreviated terms..... 3
- 5 RS-LSADS architecture..... 4
- 6 Functions of RS-LSADS..... 6
 - 6.1 General..... 6
 - 6.2 Remote monitoring..... 6
 - 6.3 Remote assistance..... 6
 - 6.4 Remote driving..... 6
- 7 RS-LSADS functional scenarios..... 7
 - 7.1 Remote support scenarios..... 7
 - 7.1.1 Scenario 1: Re-starting after stopping at the bus bay..... 7
 - 7.1.2 Scenario 2: Entering the unsignalized intersection..... 8
 - 7.1.3 Scenario 3: Entering the signalized intersection (signal information only)..... 9
 - 7.1.4 Scenario 4: Entering the signalized intersection (signal information and both lateral directions check)..... 9
 - 7.1.5 Scenario 5: Bypassing obstacles that block the vehicle path..... 10
 - 7.1.6 Scenario 6: Out of ODD due to environmental conditions..... 11
- 8 System requirements..... 12
 - 8.1 General..... 12
 - 8.2 RS-LSADS state transition diagram..... 12
 - 8.2.1 State functional descriptions..... 14
 - 8.2.2 State transition descriptions..... 15
- 9 Communication performance for remote support..... 16
 - 9.1 General..... 16
 - 9.2 Latency in remote support..... 17
 - 9.3 End-to-end information latency..... 17
 - 9.4 Information update rate..... 18
 - 9.5 Distance error due to latency..... 18
 - 9.6 Communication messages for remote support..... 19
 - 9.6.1 Vehicle data..... 19
 - 9.6.2 LSADS data..... 20
 - 9.6.3 Driving environment data..... 20
 - 9.6.4 Driving environment audio and video information..... 20
 - 9.6.5 Passenger status onboard audio and video information..... 20
 - 9.6.6 Remote assistance data..... 20
 - 9.6.7 Remote driving control data..... 20
 - 9.6.8 Infrastructure sensors data..... 20
 - 9.6.9 Infrastructure audio and video information..... 20

10	RS-LSADS performance requirements	21
10.1	Remote monitoring performance	21
10.1.1	End-to-end communication requirement during remote assistance standby or remote driving standby	21
10.2	Remote assistance performance	21
10.2.1	Monitoring data for remote assistant	21
10.2.2	Roles of remote assistant	21
10.2.3	Remote assistant response to RFI	22
10.2.4	Remote assistance HMI, and video field of view and audio	23
10.2.5	End-to-end communication requirements during remote assistance	23
10.2.6	Data storage requirements for remote assistance	23
10.3	Remote driving performance	24
10.3.1	Monitoring data for remote driver	24
10.3.2	Remote driving response to RFD	24
10.3.3	Remote driving HMI, video field of view and audio	24
10.3.4	End-to-end communication requirements during remote driving	25
10.3.5	Limitations of remote driving	25
10.3.6	Alert and warning in remote driving	25
10.3.7	Data storage requirements for remote driving	25
11	Scenario evaluation test procedures	25
11.1	General	25
11.2	Test conditions	26
11.2.1	Subject vehicle conditions	26
11.2.2	Target vehicle or objects conditions	26
11.2.3	Environmental conditions	26
11.2.4	End-to-end communication setup for scenario tests	26
11.3	Test procedures	27
11.3.1	General	27
11.3.2	Tests for remote assistance	27
11.3.3	Tests for Remote driving	38
	Annex A (informative) An Example of RS-LSADS Implementation	46
	Annex B (informative) An example of the interaction between the control centre and the vehicle for LSADS equipped vehicle mobility service	47
	Annex C (informative) Examples of remote support required scenarios and specific operations by RS-LSADS	49
	Bibliography	57