ISO 15765-5:2023-11 (E)

Road vehicles - Diagnostic communication over Controller Area Network (DoCAN) - Part 5: Specification for an in -vehicle network connected to the diagnostic link connector

Contents

Page

Foreword iv

Introduction v

1 Scope 1

2 Normative references 1

3 Terms and definitions 1

4 Symbols and abbreviated terms 2
4.1 Symbols 2
4.2 Abbreviated terms 2

5 Conventions 4

6 In-vehicle network to external test equipment connection 4
6.1 Connectivity scenarios between external test equipment and vehicle 4
6.2 Technical requirements overview 4
6.3 ASP -- Data.req, Data.ind and Data.conf service interface 5
6.4 ASP -- Parameter mapping and configuration of OSI layers 5
6.5 Transport layer (TL) 6
6.5.1 TL - Data interface primitive parameter mapping 6
6.5.2 TL - Message segmentation 6
6.5.3 TL - ISO 15765-2 segment flow control 6
6.6 Network layer (NL) 6
6.6.1 NL - Data interface primitive parameter mapping 6
6.6.2 NL - ISO 15765-2 network layer services 7
6.6.3 NL - ISO 15765-2 network layer timing parameters 7
6.6.4 NL - ISO 15765-2 uniqueness of node diagnostic address 7
6.6.5 NL - ISO 15765-2 supported addressing formats 7
6.7 Data link layer (DLL) 8
6.7.1 DLL - Data interface primitive parameter mapping 8
6.7.2 DLL - Service interface parameter requirements 9
6.7.3 DLL - Device acceptance of CAN identifier 10
6.8 Physical layer (PHY) 10
6.8.1 PHY - Classical CAN 10
6.8.2 PHY - CAN FD 12
6.8.3 PHY - Physical media attachment (PMA) requirements 14
6.8.4 PHY - Physical media dependent (PMD) sub-layer requirements 15

Annex A (informative) Compatibility between test equipment and in-vehicle network connected to diagnostic link connector 17

Bibliography 18