

ISO 10392:2011-03 (E)

Road vehicles - Determination of centre of gravity

| Contents | | Page |
|-----------------------|--|-------------|
| Foreword | | iv |
| Introduction | | v |
| 1 | Scope | 1 |
| 2 | Normative references | 1 |
| 3 | Terms and definitions | 1 |
| 4 | Test conditions and preliminary measurements | 1 |
| 4.1 | Operating and other liquids | 1 |
| 4.2 | Preliminary measurements | 1 |
| 5 | Determination of coordinates in horizontal plane | 2 |
| 5.1 | Location of CG longitudinally | 2 |
| 5.2 | Location of CG laterally | 2 |
| 6 | Determination of CG height: Axle lift method | 2 |
| 6.1 | Loading conditions, suspensions and mechanical parts | 2 |
| 6.2 | Measuring procedure | 3 |
| 6.3 | Accuracy of determined parameters | 4 |
| 6.4 | Determination of axle load and lifting angle | 4 |
| 6.5 | Location of CG above ground | 4 |
| 6.6 | Data presentation | 5 |
| 7 | Determination of CG height: Stable pendulum method | 5 |
| 7.1 | General | 5 |
| 7.2 | Loading conditions, vehicle restraints, and mechanical parts | 6 |
| 7.3 | Measuring procedure | 6 |
| 7.4 | Accuracy of determined parameters | 7 |
| 7.5 | Determination of platform properties | 7 |
| 7.6 | Determination of applied torque | 7 |
| 7.7 | Consideration of platform deflection | 8 |
| 7.8 | Location of CG above ground | 8 |
| 7.9 | Data presentation | 8 |
| Annex A (informative) | Example of test report -- Axle lift method | 9 |
| Annex B (informative) | Example of test report -- Stable pendulum method | 11 |
| Bibliography | | 13 |