ISO 15136-2:2006-06 (E)

Petroleum and natural gas industries - Progressing cavity pump systems for artificial lift - Part 2: Surface-drive systems

Contents

Page

Foreword iv

Introduction v

1 Scope 1

2 Normative references 1

3 Terms and definitions 2

4 Abbreviated terms 5

5 Functional specification 6
5.1 General 6
5.2 Surface-drive system type selection 6
5.3 Functional characteristics 6
5.4 Environmental compatibility 7
5.5 Compatibility with related well equipment 7
5.6 Design validation and product functional testing 7
5.7 Quality control documentation 7

6 Technical specification 8
6.1 General requirements 8
6.2 Technical characteristics 8
6.3 Design criteria 8
6.4 Design verification 10
6.5 Design validation 10
6.6 Product functional test 10
6.7 Additional testing 11
6.8 Allowable design changes 11
6.9 Design scaling 11

7 Supplier requirements 11
7.1 General 11
7.2 Documentation and data control 11
7.3 Product identification 13
7.4 Quality control documentation 13
7.5 Design verification 17
7.6 Product functional testing 17

8 Repair 17

9 Preparation for shipment 17

10 Product application changes 17

Annex A (normative) Requirements for elastomers and non-metallic materials 18

Annex B (informative) Brake system evaluation method 20

Annex C (informative) Installation guidelines 34

Annex D (informative) Operation guidelines 36

Annex E (informative) Equipment selection guidelines 38

Annex F (informative) User/purchaser functional specification form 39

Annex G (informative) Brake system test methods 41

Annex H (informative) Selection and use of sucker rods in PCP rotary pumping applications 44

Bibliography 49