

ISO 22166-201:2024-02 (E)

Robotics - Modularity for service robots - Part 201: Common information model for modules

Contents		Page
Foreword		iv
Introduction		v
1	Scope	1
2	Normative references	1
3	Terms and definitions	1
4	Common information model for modules	3
4.1	General	3
4.2	Relationship between CIM and specific IMs	6
4.3	Class for common information model	7
4.3.1	General	7
4.3.2	Class for module ID	9
4.3.3	Class for properties	10
4.3.4	Class for input and output variables	11
4.3.5	Class for status	13
4.3.6	Class for services	14
4.3.7	Class for infrastructure	17
4.3.8	Class for safety and security	19
4.3.9	Class for modelling	24
4.3.10	Class for executable form	25
	Annex A (normative) Naming rules	27
	Annex B (normative) Assignment rule of a module ID	28
	Annex C (normative) Representation of common information	30
	Annex D (informative) How to use information models	54
	Annex E (informative) Format for representation of a class	57
	Bibliography	58