ISO 11593:2022-02 (E)

Robots for industrial environments - Automatic end effector exchange systems - Vocabulary

Contents

Page

Foreword ..... **iv**

Introduction ..... **v**

1 Scope **1**

2 Normative references **1**

3 Terms and definitions **1**

3.1 General terms and definitions 1
3.2 Terms related to the external shape and main dimensions of the exchange system 2
3.3 Terms related to positioning and orientation in coupling 3
3.4 Terms related to coupling and releasing forces 5
3.5 Terms related to mass and inertia of the coupled system 6
3.6 Terms related to tolerances and uncertainty 7
3.7 Terms related to magazine interfaces of the tool-mounted part 12
3.8 Terms related to tool exchange timing 14

4 Symbols **17**

4.1 Coupling parameters 17
4.2 Forces 17
4.3 Mass 18
4.4 Mechanical interface frame 18
4.5 Tool frame 18
4.6 Motion start 18
4.7 Motion timing 18

Bibliography **19**