

ISO 11593:2022-02 (E)

Robots for industrial environments - Automatic end effector exchange systems - Vocabulary

Contents		Page
Foreword.....		iv
Introduction.....		v
1	Scope	1
2	Normative references	1
3	Terms and definitions	1
3.1	General terms and definitions.....	1
3.2	Terms related to the external shape and main dimensions of the exchange system.....	2
3.3	Terms related to positioning and orientation in coupling.....	3
3.4	Terms related to coupling and releasing forces.....	5
3.5	Terms related to mass and inertia of the coupled system.....	6
3.6	Terms related to tolerances and uncertainty.....	7
3.7	Terms related to magazine interfaces of the tool-mounted part.....	12
3.8	Terms related to tool exchange timing.....	14
4	Symbols	17
4.1	Coupling parameters.....	17
4.2	Forces.....	17
4.3	Mass.....	18
4.4	Mechanical interface frame.....	18
4.5	Tool frame.....	18
4.6	Motion start.....	18
4.7	Motion timing.....	18
Bibliography.....		19