

ISO 21815-1:2022-01 (E)

Earth-moving machinery - Collision warning and avoidance - Part 1: General requirements

Contents		Page
Foreword		v
Introduction		vi
1	Scope	1
2	Normative references	1
3	Terms and definitions	2
4	Performance requirements	4
4.1	General requirements	4
4.1.1	General	4
4.1.2	Electro-magnetic compatibility (EMC)	4
4.1.3	Environmental condition requirements	4
4.1.4	Functional safety	4
4.1.5	Risk assessment	4
4.1.6	Analysis on machine modification	5
4.2	Requirements on CxS	5
4.2.1	General	5
4.2.2	Detection of intended objects	5
4.2.3	Collision risk levels and CxS actions	5
4.2.4	System limitations	5
4.3	Outline of process flow for CxS	6
4.4	False CxS actions	6
4.5	Operating state transition of CxS	6
4.5.1	General	6
4.5.2	Switching between normal mode and stand-by mode	6
4.5.3	Switching between normal mode to override mode	7
4.5.4	Status information	7
4.6	Self-checking, status indication and failure warning	7
4.7	Protection against unauthorized modification of system functions	8
5	System classification	8
5.1	General	8
5.2	System capability types	8
5.2.1	Take-off inhibition CxS (TIC)	8
5.2.2	Swing inhibition CxS (SIC)	8
5.2.3	Manoeuvring speed CxS (MSC)	8
5.2.4	Travel speed CxS (TSC)	8
5.3	System types	9
5.4	Types of detection	9
5.5	Description of systems	9
6	Test procedures	9
6.1	General	9
6.2	Test condition	9
6.2.1	Test environment condition	9
6.2.2	Test surface conditions	9
6.3	Subject machine conditions	10
6.4	Specification of test objects	10

6.5	Performance test	10
6.5.1	General	10
6.5.2	Test object installation	10
6.5.3	Subject machine	10
6.5.4	Test result judgement criteria	10
6.6	False positive CxS action test	10
7	CxS information for use	11
7.1	Information for the operator	11
ISO 21815-1:2022(E) ISO 21815-1:2022(E) 7.2 Information about residual risks		11
Annex A (informative) Machine interaction scenario common examples		12
Annex B (informative) Comparison of system functions		14
Annex C (informative) Example of operator's manual		15
Bibliography		17