

ISO 23509:2016-11 (E)

Bevel and hypoid gear geometry

Contents		Page
Foreword		v
Introduction		vi
1	Scope	1
2	Normative references	1
3	Terms, definitions and symbols	1
3.1	Terms and definitions	5
3.2	Symbols	7
4	Design considerations	9
4.1	General	9
4.2	Types of bevel gears	10
4.2.1	General	10
4.2.2	Straight bevels	10
4.2.3	Spiral bevels	10
4.2.4	Zerol bevels	10
4.2.5	Hypoids	11
4.3	Ratios	11
4.4	Hand of spiral	11
4.5	Preliminary gear size	12
5	Tooth geometry and cutting considerations	12
5.1	Manufacturing considerations	12
5.2	Tooth taper	12
5.3	Tooth depth configurations	14
5.3.1	Taper depth	14
5.3.2	Uniform depth	15
5.4	Dedendum angle modifications	17
5.5	Cutter radius	17
5.6	Mean radius of curvature	17
5.7	Hypoid design	18
5.8	Most general type of gearing	18
5.9	Hypoid geometry	19
5.9.1	Basics	19
5.9.2	Crossing point	21
6	Pitch cone parameters	21
6.1	Initial data for pitch cone parameters	21
6.2	Determination of pitch cone parameters for bevel and hypoid gears	22
6.2.1	Method 0	22
6.2.2	Method 1	22
6.2.3	Method 2	26
6.2.4	Method 3	31
7	Gear dimensions	33
7.1	Initial data for tooth profile parameters	33
7.2	Determination of basic data	36
7.3	Determination of tooth depth at calculation point	38
7.4	Determination of root angles and face angles	38

7.5	Determination of pinion face width, b_1	40
7.6	Determination of inner and outer spiral angles	42
7.6.1	Pinion	42
7.6.2	Wheel	43
7.7	Determination of tooth depth	44
7.8	Determination of tooth thickness	44
7.9	Determination of remaining dimensions	46
8	Undercut check	47
8.1	Pinion	47
8.2	Wheel	49
Annex A (informative) Structure of ISO formula set for calculation of geometry data of bevelandhypoidgears		51
Annex B (informative) Pitch cone parameters		57
Annex C (informative) Gear dimensions		68
Annex D (informative) Analysis of forces		75
Annex E (informative) Machine tool data		78
Annex F (informative) Sample calculations		79
Bibliography		138