ISO 23509:2016-11 (E)

Bevel and hypoid gear geometry

Contents

Page

Foreword v

Introduction vi

1 Scope 1

2 Normative references 1

3 Terms,definitionsandsymbols 1
3.1 Terms and definitions 5
3.2 Symbols 7

4 Design considerations 9
4.1 General 9
4.2 Types of bevel gears 10
4.2.1 General 10
4.2.2 Straight bevels 10
4.2.3 Spiral bevels 10
4.2.4 Zerol bevels 10
4.2.5 Hypoids 11
4.3 Ratios 11
4.4 Hand of spiral 11
4.5 Preliminary gear size 12

5 Tooth geometry and cutting considerations 12
5.1 Manufacturing considerations 12
5.2 Tooth taper 12
5.3 Tooth depth configurations 14
5.3.1 Taper depth 14
5.3.2 Uniform depth 15
5.4 Dedendum angle modifications 17
5.5 Cutter radius 17
5.6 Mean radius of curvature 17
5.7 Hypoid design 18
5.8 Most general type of gearing 18
5.9 Hypoid geometry 19
5.9.1 Basics 19
5.9.2 Crossing point 21

6 Pitch cone parameters 21
6.1 Initial data for pitch cone parameters 21
6.2 Determination of pitch cone parameters for bevel and hypoid gears 22
6.2.1 Method 0 22
6.2.2 Method 1 22
6.2.3 Method 2 26
6.2.4 Method 3 31

7 Gear dimensions 33
7.1 Initial data for tooth profile parameters 33
7.2 Determination of basic data 36
7.3 Determination of tooth depth at calculation point 38
7.4 Determination of root angles and face angles 38

7.5 Determination of pinion face width, b1 40
7.6 Determination of inner and outer spiral angles 42
7.6.1 Pinion 42
7.6.2 Wheel 43
7.7 Determination of tooth depth 44
7.8 Determination of tooth thickness 44
7.9 Determination of remaining dimensions 46

8 Undercut check 47
8.1 Pinion 47
8.2 Wheel 49

Annex A (informative) Structure of ISO formula set for calculation of geometry data of bevelandhypoidgears 51

Annex B (informative) Pitch cone parameters 57

Annex C (informative) Gear dimensions 68

Annex D (informative) Analysis of forces 75

Annex E (informative) Machine tool data 78

Annex F (informative) Sample calculations 79

Bibliography 138