

ISO 10218-2:2011-07 (E)

Robots and robotic devices - Safety requirements for industrial robots - Part 2: Robot systems and integration

Contents		Page
Foreword		iv
Introduction		v
1	Scope	1
2	Normative references	1
3	Terms and definitions	2
4	Hazard identification and risk assessment	4
4.1	General	4
4.2	Layout design	5
4.3	Risk assessment	6
4.4	Hazard identification	8
4.5	Hazard elimination and risk reduction	9
5	Safety requirements and protective measures	9
5.1	General	9
5.2	Safety-related control system performance (hardware/software)	9
5.3	Design and installation	10
5.4	Limiting robot motion	14
5.5	Layout	16
5.6	Robot system operational mode application	17
5.7	Pendants	21
5.8	Maintenance and repair	22
5.9	Integrated manufacturing system (IMS) interface	23
5.10	Safeguarding	24
5.11	Collaborative robot operation	32
5.12	Commissioning of robot systems	35
6	Verification and validation of safety requirements and protective measures	36
6.1	General	36
6.2	Verification and validation methods	37
6.3	Required verification and validation	37
6.4	Verification and validation of protective equipment	37
7	Information for use	38
7.1	General	38
7.2	Instruction handbook	39
7.3	Marking	43
Annex A (informative)	List of significant hazards	44
Annex B (informative)	Relationship of standards related to protective devices	47
Annex C (informative)	Safeguarding material entry and exit points	49
Annex D (informative)	Operation of more than one enabling device	52
Annex E (informative)	Conceptual applications of collaborative robots	53

Annex F (informative) Process observation	55
Annex G (normative) Means of verification of the safety requirements and measures	58
Bibliography	71