

ISO 16063-15:2006-08 (E)

Methods for the calibration of vibration and shock transducers - Part 15: Primary angular vibration calibration by laser interferometry

Contents		Page
Foreword	iv
1	Scope	1
2	Normative references	2
3	Uncertainty of measurement	2
4	Requirements for apparatus	2
4.1	General	2
4.2	Frequency generator and indicator	3
4.3	Power amplifier/angular vibration exciter combination	3
4.4	Seismic block(s) for vibration exciter and laser interferometer	5
4.5	Laser	5
4.6	Interferometer	5
4.7	Instrumentation for interferometer signal processing	8
4.8	Voltage instrumentation, measuring true r.m.s. accelerometer output	9
4.9	Distortion-measuring instrumentation	9
4.10	Oscilloscope (optional)	9
4.11	Other requirements	9
5	Ambient conditions	9
6	Preferred angular accelerations and frequencies	10
7	Common procedure for all six methods	10
8	Methods using fringe-counting (methods 1A and 1B)	11
8.1	General	11
8.2	Common test procedure for methods 1A and 1B	12
8.3	Expression of results	12
9	Methods using minimum-point detection (methods 2A and 2B)	16
9.1	General	16
9.2	Common test procedure for methods 2A and 2B	17
9.3	Expression of results	17
10	Methods using sine approximation (methods 3A and 3B)	21
10.1	General	21
10.2	Procedure applied to methods 3A and 3B	22
10.3	Data acquisition	27
10.4	Data processing	27
11	Reporting of calibration results	29
Annex A (normative)	Uncertainty components in primary angular vibration calibration of vibration and shock transducers by laser interferometry	30
Annex B (normative)	Equations for the calculation of the angular quantities of rotational angle, , angular velocity, , and angular acceleration, , and of the sensitivities of angular transducers: rotational angle transducers, S, of angular velocity transducers, S, and angular accelerometers, S	36
Bibliography	42