ISO 21940-1:2019 (E)

Mechanical vibration — Rotor balancing — Part 1: Introduction

Contents

Foreword

Introduction

- 1 Scope
- 2 Normative references
- 3 Terms and definitions
- 4 Fundamentals of balancing
 - 4.1 General
 - 4.2 Unbalance of a single disc
 - 4.3 Unbalance distribution
 - 4.4 Unbalance representation
- 5 Factors to consider when balancing
 - 5.1 General
 - 5.2 Rotors with rigid behaviour
 - 5.3 Rotors with flexible behaviour
 - 5.3.1 General
 - 5.3.2 Shaft-elastic behaviour
 - 5.3.3 Component-elastic behaviour
 - 5.3.4 Settling behaviour
 - 5.4 Examples of rotor behaviours
- 6 Selection of a balancing procedure

7 Unbalance tolerances

- 7.1 General
- 7.2 Permissible residual unbalance
- 7.2.1 General
- 7.2.2 Permissible residual unbalance for rotors with rigid behaviour
- 7.2.3 Permissible residual unbalance for rotors with flexible behaviour
- 7.3 Vibration limits
- 7.4 Influence of modes above service speed
- 7.5 Factors influencing balancing procedures
- 7.5.1 General
- 7.5.2 Tolerances
- 7.5.3 Speed and support conditions
- 7.5.4 Initial unbalance
- 8 Selection of a balancing machine
 - 8.1 General
 - 8.2 Special requirements

9 International Standards on balancing

- 9.1 General
- 9.2 Vocabulary
- 9.2.1 ISO 21940-2 Balancing vocabulary
- 9.2.2 ISO 2041 Vibration and shock vocabulary
- 9.3 Balancing procedures and tolerances
- 9.3.1 General
- 9.3.2 ISO 21940-11 Procedures and tolerances for rotors with rigid behaviour

- 9.3.3 ISO 21940-12 Procedures and tolerances for rotors with flexible behaviour
- 9.3.4 ISO 21940-13 Criteria and safeguards for the in-situ balancing of medium and large rotors
- 9.3.5 ISO 21940-14 Procedures for addressing balancing errors
- 9.4 Balancing machines
- 9.4.1 ISO 21940-21 Description and evaluation of balancing machines
- 9.4.2 ISO 21940-23 Enclosures and other protective measures for the measuring station of balancing machines
- 9.5 Machine design for balancing
- 9.5.1 ISO 21940-31 Susceptibility and sensitivity of machines to unbalance
- 9.5.2 ISO 21940-32 Shaft and fitment key convention

Annex A (informative) Mathematical and graphical representation of unbalance

- A.1 Notation
- A.2 Objective
- A.3 Unbalance vectors
- A.4 Moment unbalance
- A.5 Couple unbalance
- A.6 Modal unbalances
- A.6.1 Mode shapes
- A.6.2 Modal unbalance representation
- A.6.3 Equivalent modal unbalance
- Annex B (informative) Examples of different rotor behaviours as indicated on a typical hard#bearing balancing machine
 - B.1 General
 - B.2 Rigid behaviour
 - B.3 Flexible behaviour
 - B.3.1 General
 - B.3.2 Flexible behaviour where the service speed is below the rotor's first bending resonance
 - B.3.3 Flexible behaviour where the service speed is above the rotor's first bending resonance
 - B.4 Component-elastic behaviour of components
 - B.5 Settling behaviour

Page count: 30