

Contents

	Foreword
	Introduction
1	Scope
2	Normative references
3	Terms and definitions
4	Fundamentals of balancing
4.1	General
4.2	Unbalance of a single disc
4.3	Unbalance distribution
4.4	Unbalance representation
5	Factors to consider when balancing
5.1	General
5.2	Rotors with rigid behaviour
5.3	Rotors with flexible behaviour
5.3.1	General
5.3.2	Shaft-elastic behaviour
5.3.3	Component-elastic behaviour
5.3.4	Settling behaviour
5.4	Examples of rotor behaviours
6	Selection of a balancing procedure
7	Unbalance tolerances
7.1	General
7.2	Permissible residual unbalance
7.2.1	General
7.2.2	Permissible residual unbalance for rotors with rigid behaviour
7.2.3	Permissible residual unbalance for rotors with flexible behaviour
7.3	Vibration limits
7.4	Influence of modes above service speed
7.5	Factors influencing balancing procedures
7.5.1	General
7.5.2	Tolerances
7.5.3	Speed and support conditions
7.5.4	Initial unbalance
8	Selection of a balancing machine
8.1	General
8.2	Special requirements
9	International Standards on balancing
9.1	General
9.2	Vocabulary
9.2.1	ISO 21940-2 — Balancing vocabulary
9.2.2	ISO 2041 — Vibration and shock vocabulary
9.3	Balancing procedures and tolerances
9.3.1	General
9.3.2	ISO 21940-11 — Procedures and tolerances for rotors with rigid behaviour

- 9.3.3 ISO 21940-12 — Procedures and tolerances for rotors with flexible behaviour
- 9.3.4 ISO 21940-13 — Criteria and safeguards for the in-situ balancing of medium and large rotors
- 9.3.5 ISO 21940-14 — Procedures for addressing balancing errors
- 9.4 Balancing machines
- 9.4.1 ISO 21940-21 — Description and evaluation of balancing machines
- 9.4.2 ISO 21940-23 — Enclosures and other protective measures for the measuring station of balancing machines
- 9.5 Machine design for balancing
- 9.5.1 ISO 21940-31 — Susceptibility and sensitivity of machines to unbalance
- 9.5.2 ISO 21940-32 — Shaft and fitment key convention

Annex A (informative) Mathematical and graphical representation of unbalance

- A.1 Notation
- A.2 Objective
- A.3 Unbalance vectors
- A.4 Moment unbalance
- A.5 Couple unbalance
- A.6 Modal unbalances
- A.6.1 Mode shapes
- A.6.2 Modal unbalance representation
- A.6.3 Equivalent modal unbalance

Annex B (informative) Examples of different rotor behaviours as indicated on a typical hard#bearing balancing machine

- B.1 General
- B.2 Rigid behaviour
- B.3 Flexible behaviour
- B.3.1 General
- B.3.2 Flexible behaviour where the service speed is below the rotor's first bending resonance
- B.3.3 Flexible behaviour where the service speed is above the rotor's first bending resonance
- B.4 Component-elastic behaviour of components
- B.5 Settling behaviour

Page count: 30