ISO 11898-4:2004-08 (E)

Road vehicles - Controller area network (CAN) - Part 4: Time-triggered communication

Contents

Page

Foreword iv

Introduction v

1 Scope 1

2 Normative references 1

3 Terms and definitions 1

4 Abbreviated terms 6

5 Basic concepts of time-triggered CAN 6
5.1 General conventions 6
5.2 General principle of protocol 8
5.3 Reference message 10

6 Timing and synchronisation features 12
6.1 Levels 1 and 2 12
6.2 Generation of local time 12
6.3 Cycle_Time parameter 14
6.4 Synchronisation in Level 2 14
6.5 Global time in Level 2 (local time + local offset) 14
6.6 External clock synchronisation 15

7 Sending and receiving 15
7.1 General 15
7.2 Transmission of messages 15
7.3 Reception of messages 17
7.4 Transmission of reference messages 17

8 Initialisation and fault tolerance of time masters 18
8.1 General 18
8.2 Initialisation procedure 19
8.3 Failure of current time master 20
8.4 Shutdown 20

9 Failure handling 21
9.1 General 21
9.2 Message status count 22
9.3 Interrupt_Status_Vector 22
9.4 Master state 23

10 Visible interfaces 25
10.1 Configuration interfaces 25
10.2 Application interfaces 28
10.3 Optional interfaces 30

Bibliography 32