

ISO/PAS 11585:2023-09 (E)

Road vehicles - Partial driving automation - Technical characteristics of conditional hands-free driving systems

Contents		Page
Foreword		iv
Introduction		v
1	Scope	1
2	Normative references	1
3	Terms and definitions	1
4	Functionality	3
4.1	Overall system context	3
4.2	General requirements	5
4.3	State: L2 hands-free	6
4.3.1	Control loop	6
4.3.2	Possibility for the driver to deactivate, overrule and override the L2 hands-free state	6
4.3.3	ODD monitoring	7
4.3.4	Driver monitoring	7
4.3.5	Driver information and warning	7
4.4	Transitions	8
4.4.1	Enter "L2 hands-free state" from "manual-driving mode", "L1-driving mode" or "PADS active-driving mode"	8
4.4.2	Leaving "L2 hands-free state" due to drivers' intervention	8
4.4.3	Leaving "L2 hands-free state" due to system intervention	8
4.4.4	Leaving "L2 hands-free state" due to risk-mitigation	9
5	Technical characteristics of "L2 hands-free subsystems"	9
5.1	Driver-monitoring system	9
5.2	Driver information and warning system	10
5.3	ODD-monitoring system	10
5.4	Risk-mitigation system	11
Annex A (informative) Driver information and warning system		12
Bibliography		14