

ISO/TS 15638-12:2013-08 (E)

Intelligent transport systems - Framework for collaborative Telematics Applications for Regulated commercial freight Vehicles (TARV) - Part 12: Vehicle mass monitoring (VMM)

Contents		Page
1	Scope	1
2	Conformance	1
3	Normative references	2
4	Terms and definitions	2
5	Symbols (and abbreviated terms)	8
6	General overview and framework requirements	9
7	Requirements for services using generic vehicle data	9
8	Application services that require data in addition to basic vehicle data	10
8.1	General	10
8.2	Quality of service requirements	10
8.3	Test requirements	10
8.4	Marking, labelling and packaging	10
9	Common features of regulated TARV application services	10
9.1	General	10
9.2	Common role of the jurisdiction, approval authority, service provider and user	11
9.3	Common characteristics for instantiations of regulated application services	11
9.4	Common sequence of operations for regulated application services	11
9.5	Quality of service	12
9.6	Information security	12
9.7	Data naming content and quality	12
9.8	Software engineering quality systems	12
9.9	Quality monitoring station	12
9.10	Audits	12
9.11	Access control to data policy	12
9.12	Approval of IVSs and service providers	12
10	Vehicle mass monitoring (VMM)	12
10.1	TARV VMM service description and scope	12
10.1.1	TARV VMM use case	12
10.1.2	Description of TARV VMM regulated application service	13
10.1.3	Description of TARV 'Vehicle mass monitoring' (TARV VMM) application service	14
10.2	Concept of operations for TARV VMM	14
10.2.1	General	14
10.2.2	Statement of the goals and objectives of the TARV VMM system	15
10.2.3	Strategies, tactics, policies, and constraints affecting the TARV VMM system	15
10.2.4	Organisations, activities, and interactions among participants and stakeholders for TARV VMM	16
10.2.5	Clear statement of responsibilities and authorities delegated for TARV VMM	17
10.2.6	Equipment required for TARV VMM	17
10.2.7	Calibration of mass sensors	24
10.2.8	Alarm Records for TARV VMM	25

10.2.9	Operational processes for the TARV VMM system	26
10.2.10	Role of the jurisdiction for TARV VMM	26
10.2.11	1Role of the TARV VMM prime service provider	26
10.2.12	Role of the TARV VMM application service provider	27
10.2.13	Role of the TARV VMM user	27
10.2.14	Generic characteristics for all instantiations of the TARV VMM application service	27
10.3	Sequence of operations for TARV VMM	27
10.3.1	General	27
10.4	TARV VMM service elements	29
10.4.1	TARV VMM service element (SE) 1: Establish `Vehicle mass monitoring' regulations, requirements, and Approval arrangements	29
10.4.2	TARV VMM SE2: Request system approval	29
10.4.3	TARV VMM SE3: User (operator) contracts with prime service provider	29
10.4.4	TARV VMM SE4: User (operator) equips vehicle with a devices to provide load information	29
10.4.5	TARV VMM SE5: User contracts with application service provider	29
10.4.6	TARV VMM SE6: application service provider uploads software into the TARV equipped vehicles of the operator	29
10.4.7	TARV VMM SE7: Time series or application service instigated recording of vehicle load .	29
10.4.8	TARV VMM SE8: `Interrogated' request for vehicle mass monitoring data	30
10.5	Generic TARV VMM data naming content and quality	31
10.6	TARV VMM application service specific provisions for quality of service	32
10.6.1	General	32
10.6.2	Tamper evidency	33
10.7	TARV VMM application service specific provisions for test requirements	33
10.8	TARV VMM application specific rules for the Approval of IVSs and `Service Providers'	33
11	Declaration of patents and intellectual property	33
Annex A (Informative) Independent testing of the protocols defined in this Part of ISO 15638		34
A.1	Objectives	34
A.2	TEST SCRIPT 6 SERVICE: VMM VEHICLE MASS MONITORING	36
CTP 6.1.1 Instigated Vehicle Mass Monitoring using 2G		38
CTP 6.1.2 Interrogated Vehicle Mass Monitoring using 2G		40
CTP 6.1.3 Interrogated Vehicle Mass Monitoring using 5.9GHz and responding using 2G or 3G		42
CTP 6.2.1 Instigated Vehicle Mass Monitoring using 3G		44
CTP 6.2.2 Interrogated at 5.9 GHz and send of Vehicle Mass Monitoring using 3G		46
CTP 6.3.1 Instigated Vehicle Mass Monitoring using 802.11p (WAVE) 5.9 GHz		48
CTP 6.3.2 Interrogated Vehicle Mass Monitoring using 802.11p (WAVE) 5.9 GHz		50
CTP 6.4.1 Instigated Vehicle Mass Monitoring using Mesh WiFi		52
CTP 6.4.2 Interrogated Vehicle Mass Monitoring using Mesh WiFi		54
Bibliography		56