

# DIN EN 15213-1:2013-08 (E)

## Intelligent transport systems - After-theft systems for the recovery of stolen vehicles - Part 1: Reference architecture and terminology

---

<b>Contents</b>		<b>Page</b>
Foreword .....		3
Introduction .....		4
<b>1</b>	<b>Scope .....</b>	<b>5</b>
<b>2</b>	<b>Normative references .....</b>	<b>5</b>
<b>3</b>	<b>Terms and definitions .....</b>	<b>5</b>
3.1	General definitions .....	5
3.2	Basic ATSVR Functions .....	7
3.3	Optional ATSVR Functions .....	8
3.4	ATSVR Services .....	10
3.5	ATSVR Communications .....	10
3.6	ATSVR Status .....	10
3.7	Interoperability and Compatibility .....	11
<b>4</b>	<b>Symbols and abbreviations .....</b>	<b>11</b>
<b>5</b>	<b>ATSVR Conceptual Architecture Model .....</b>	<b>12</b>
5.1	General .....	12
5.2	Functions within the process .....	12
5.3	Short- and Long-Range Concepts .....	13
5.3.1	ATSVR Operations with Short-Range Concept .....	13
5.3.2	ATSVR Operations with Long-Range Concept .....	13
	<b>Bibliography .....</b>	<b>16</b>