

ISO 17458-4:2013-02 (E)

Road vehicles - FlexRay communications system - Part 4: Electrical physical layer specification

Contents	Page
Foreword	v
Introduction	vi
1 Scope	1
2 Normative references	1
3 Terms, definitions, symbols and abbreviated terms	1
3.1 Terms and definitions	1
3.2 Abbreviated terms	10
3.3 Symbols	12
4 Document reference according to OSI model	13
5 Conventions	14
5.1 General	14
5.2 Notational and parameter prefix conventions	14
5.3 Important preliminary notes	15
6 Communication channel basics	16
6.1 Objective	16
6.2 Propagation delay	16
6.3 Frame TSS length change	18
6.4 Symbol length change	18
6.5 FES1 length change	19
6.6 Collisions	19
6.7 Stochastic jitter	20
6.8 Wakeup patterns	20
7 Principle of FlexRay networking	22
7.1 Objective	22
7.2 Interconnection of nodes	22
7.3 Electrical signalling	23
8 Network components	24
8.1 Objective	24
8.2 Cables	24
8.3 Connectors	25
8.4 Cable termination	25
8.5 Termination concept	27
8.6 Common mode chokes	27
8.7 DC bus load	27
9 Network topology	28
9.1 Objective	28
9.2 Point-to-point connection	29
9.3 Passive star	29
9.4 Linear passive bus	30
9.5 Active star network	31
9.6 Cascaded active stars	32

9.7	Hybrid topologies	32
9.8	Dual channel topologies	33
10	Asymmetric delay budget	33
10.1	Objective	33
10.2	Basic topology for asymmetric delay budget	34
10.3	Definition of Test Planes	34
10.4	Requirements to the asymmetric delay budget	36
10.5	Definition of maximum asymmetric delay portions	36
10.6	Other networks	43
11	Signal integrity	43
11.1	Objective	43
11.2	Mask test at TP1 / TP11	44
12	Electrical bus driver	49
12.1	Overview	49
12.2	Operation modes	50
12.3	Operation mode transitions	51
12.4	Bus driver - communication controller interface	53
12.5	Bus driver - bus guardian interface (optional)	57
12.6	Bus driver - host interface	57
12.7	Bus driver - power supply interface	61
12.8	Bus driver - level shift interface (optional)	63
12.9	Bus driver - bus interface	63
12.10	Bus driver - wakeup interface (optional)	77
12.11	Remote wakeup event detector (optional)	78
12.12	Bus driver behaviour under fault conditions	80
12.13	Bus driver functional classes	85
12.14	Bus driver signal summary	87
13	Active Star	88
13.1	Overview	88
13.2	Hardware overview	88
13.3	Signal timing	90
13.4	Active star device operation modes	98
13.5	Autonomous power mode flag (APM flag)	100
13.6	Branch operating states	101
13.7	Branch transmitter and receiver circuit	104
13.8	Active star - communication controller interface (optional)	105
13.9	Active star - bus guardian interface (optional)	115
13.10	Active star - host interface (optional)	115
13.11	Active star - power supply interface	115
13.12	Active star - level shift interface (optional)	118
13.13	Active star - bus interface	118
13.14	Active star - wake interface (optional)	119
13.15	Active star functional classes	119
13.16	Active star behaviour under fault conditions	120
13.17	Active star signal summary	122
14	Interface definitions	123
14.1	Overview	123
14.2	Communication controller - bus driver interface	123
14.3	Host	126
15	General features for FlexRay physical layer parts	127
15.1	Objective	127
15.2	Voltage limits for digital output signals	127
15.3	Input voltage thresholds for digital signals	127
15.4	ESD protection on chip level (HBM)	128
15.5	ESD protection on chip level (IEC61000-4-2)	128
15.6	ESD protection on ECU level	128

15.7	Operating temperature	128
15.8	Serial peripheral interface (SPI)	129
Annex A (informative) Application notes		131